

Section 4.3A: Weak contractions and stability.

We are interested here in maps f that satisfy the inequality

$$|f(X) - \bar{x}| < \|X - \bar{X}\|, \quad X \in D \subset \mathbb{R}^m. \quad (4.3b)$$

In the case $m = 1$, this reduces to the contraction inequality

$$|f(x) - \bar{x}| < |x - \bar{x}| \quad (4.3c)$$

which we already know implies asymptotic stability for \bar{x} , if (4.3c) holds in some neighborhood U of \bar{x} . In fact, (4.3c) generalizes linearization on the line since it implies the inequality $|f'(\bar{x})| \leq 1$ when f is C^1 -smooth at \bar{x} . If the reverse of (4.3c) holds on U then \bar{x} is strongly unstable (or repelling). Special cases of (4.3b) have appeared frequently in the published literature; in this section we encounter several instances of this occurrence in both theory and applications (also see the Notes segment below). To examine the consequences of (4.3b) when $m \geq 2$ we start with a definition.

Definition 4.3.1. Let Y be a fixed point of a continuous function F on \mathbb{R}^m . We say that F is a *weak contraction at a point X relative to Y* if

$$\|F(X) - Y\| \leq \|X - Y\|, \quad (4.3d)$$

and denote by $W(F, Y)$ the (closed) set of all points for which (4.3d) is satisfied. Clearly, $W(F, Y)$ is norm dependent, but we only use the sup-norm here. For a scalar map f , we call f a *weak contraction relative to a fixed point \bar{x}* if V_f is a weak contraction relative to \bar{X} . For f we also define the set

$$A(f; \bar{x}) \doteq \{X \in \mathbb{R}^m : |f(X) - \bar{x}| < \|X - \bar{X}\|\} \cup \{\bar{X}\}.$$

Next, some basic relationships are listed in a lemma (also see the Remark following Theorem 4.3.2). The simple proof is left to the reader.

Lemma 4.3.3. *Let \bar{x} be a fixed point of f as defined by (??). Then:*

- (a) $|f(X) - \bar{x}| \leq \|V_f(X) - \bar{X}\|$ for all X ;
- (b) If x^* is a fixed point of (??), $x^* \neq \bar{x}$, then $x^* \in W(V_f, \bar{x})$ but not in $A(f; \bar{x})$;
- (c) $W(V_f, \bar{X}) = \{X : |f(X) - \bar{x}| \leq \|X - \bar{X}\|\} = \overline{A(f; \bar{x})}$.
- (d) $A(f; \bar{x})$ is open if and only if \bar{X} is in the interior of $A(f; \bar{x})$.

Note that if f is a weak contraction, then V_f is generally not a contraction (e.g., as in scalar linear maps - see Corollary 4.3.7 and the remarks preceding it); this fact has important consequences that will be discussed later on.

Lemma 4.3.3(b) shows that points in $W(V_f, \bar{X})$ that lie on the boundary of $A(f; \bar{x})$ may not be attracted to \bar{X} under the iterations of V_f . However, the next result, and Corollary 4.3.3 show that points in $A(f; \bar{x})$ itself are different.

Theorem 4.3.1. (Asymptotic stability) *Let $\bar{x} \in \mathbb{R}$ be a fixed point of (??) and let T be a closed, invariant set containing \bar{X} , and let $A \doteq A(f; \bar{x})$. Then \bar{X} is*

asymptotically stable relative to each invariant subset S of $T \cap A$ that is closed in T ; in particular, \bar{x} attracts every trajectory with a vector of initial values $(x_{1-m}, \dots, x_0) \in S$.

Proof. Let S be a T -closed, invariant subset of $T \cap A$. Then

$$|f(V_f^k(X)) - \bar{x}| < \|V_f^k(X) - \bar{X}\|. \quad (\text{T4.3.1a})$$

for all positive integers k and for every $X \in S$. Next, for $1 \leq k \leq m-1$, observe that by (??),

$$V_f^k(X) = (f(V_f^{k-1}(X)), \dots, f(X), u_1, \dots, u_{m-k}) \quad (\text{T4.3.1b})$$

for $X = (u_1, \dots, u_m) \in A$. Now, by (T4.3.1b), Lemma 4.3.3(a) and induction on k ,

$$\|V_f^k(X) - \bar{X}\| \leq \|X - \bar{X}\| \quad (\text{T4.3.1c})$$

for $k = 1, \dots, m-1$. Therefore, from (T4.3.1a), (T4.3.1c) and (??) we may conclude that

$$\begin{aligned} \|V_f^m(X) - \bar{X}\| &= \max \left\{ |f(V_f^{m-1}(X)) - \bar{x}|, \dots, |f(X) - \bar{x}| \right\} \\ &< \|X - \bar{X}\| \end{aligned} \quad (\text{T4.3.1d})$$

for all $X \in S$. Next, let $X_0 = (x_0, \dots, x_{1-m})$ be any vector of initial values for (??) in S . Then (T4.3.1d) implies that

$$\begin{aligned} \|V_f^{mn}(X_0) - \bar{X}\| &= \|V_f^m(V_f^{m(n-1)}(X_0)) - \bar{X}\| \\ &< \|V_f^{m(n-1)}(X_0) - \bar{X}\| \end{aligned}$$

for every positive integer n . Therefore, the sequence

$$\{\|V_f^{mn}(X_0) - \bar{X}\|\}, \quad n = 1, 2, 3, \dots$$

is strictly decreasing to a limit $r_0 \geq 0$ as $n \rightarrow \infty$. If $r_0 > 0$ and Ω_0 is the (forward) limit set of the vector sequence $\{V_f^{mn}(X_0)\}$, then

$$\Omega_0 \subset \partial B_{r_0}(\bar{X}) \cap S \subset T \cap A$$

where the first inclusion holds because S is closed in T . Therefore, by the invariance of Ω_0 under V_f^m , for any $Y \in \Omega_0$, (T4.3.1d) implies

$$r_0 = \|V_f^m(Y) - \bar{X}\| < \|Y - \bar{X}\| = r_0$$

which is impossible. Hence, for every $X_0 \in S$, $V_f^{mn}(X_0) \rightarrow \bar{X}$ as $n \rightarrow \infty$. By Lemmas 4.3.1 and 4.3.2,

$$V_f^{mn}(X_0) = (x_{mn-1}, \dots, x_{m(n-1)})$$

so it may be concluded that for all $i = 1, \dots, m$,

$$|x_{mn-i} - \bar{x}| \leq \|V_f^{mn}(X_0) - \bar{X}\| \rightarrow 0$$

as $n \rightarrow \infty$. It follows that $x_n \rightarrow \bar{x}$; thus \bar{X} attracts every point of S , and S is closed, so $\bar{X} \in S$. With Lemma 4.3.3(c) implying the stability of \bar{X} in the relative topology on A , the proof is complete.

Theorem 4.3.1 is valid with $T = \mathbb{R}^m$; on the other hand, in applied models, usually the cone $T = [0, \infty)^m$ is the relevant invariant set, to which attention may be restricted. It should be emphasized that if $T \neq \mathbb{R}^m$, then it is possible that $\bar{X} \in \partial T$, as in the next example. Indeed, Theorem 4.3.1 tends to be most useful when applied to such boundary equilibria (but also see Corollary 4.3.3).

Example 4.3.1. The third order equation

$$\begin{aligned} x_n &= ax_{n-1} + bx_{n-3} \exp(-cx_{n-1} - dx_{n-3}), \\ a, b, c, d &\geq 0, \quad c + d > 0 \end{aligned} \tag{E4.3.1a}$$

represents a special case of the flour beetle population model; see the Notes segment. We show that the origin is asymptotically stable (i.e., the beetles go extinct) if

$$a + b \leq 1, \quad b > 0. \tag{E4.3.1b}$$

Before proceeding, it is worth noting that the linearization of (E4.3.1a) at the origin has a unit eigenvalue $\lambda = 1$ when $a + b = 1$. Now, observe that if (E4.3.1b) holds, then for all $(x, y, z) \in [0, \infty)^3$, $(x, y, z) \neq (0, 0, 0)$,

$$\begin{aligned} ax + bz \exp(-cx - dz) &\leq [a + b \exp(-cx - dz)] \max\{x, z\} \\ &< (a + b) \max\{x, y, z\} \\ &\leq \max\{x, y, z\} \end{aligned}$$

so Theorem 4.3.1 implies that the origin is a stable global attractor of non-negative solutions. In a later segment below, we also derive sufficient conditions for the global stability of the *positive* fixed point of (E4.3.1a).

For comparison, we also obtain conditions that imply the boundedness of all solutions of (E4.3.1a). We note that if $d > 0$ then for all $x, z \geq 0$,

$$ax + bze^{-cx-dz} \leq ax + \frac{bz}{e^{dz}} \leq ax + \frac{b}{de}$$

so by Theorem 4.2.1, (E4.3.1a) is semipermanent if $0 \leq a < 1$, regardless of the value of b . Further, for each positive solution $\{x_n\}$, Lemmas 4.2.2 and 4.2.3 imply that an upper bound is the fixed point of the linear mapping $ax + b/de$, namely, $b/[de(1-a)]$.

A generalization of Example 4.3.1 is the next corollary, which in particular provides a tool for establishing the global stability of the zero equilibrium. The simple proof (showing that the map is a weak contraction) is omitted.

Corollary 4.3.1. *Let $f_i \in C([0, \infty)^m, [0, 1))$ for $i = 1, \dots, k$ and $k \geq 2$. If $\sum_{i=1}^k f_i(u_1, \dots, u_m) < 1$ for all $(u_1, \dots, u_m) \in [0, \infty)^m$ then the origin is the unique, globally asymptotically stable fixed point of the following equation:*

$$x_n = \sum_{i=1}^k f_i(x_{n-1}, \dots, x_{n-m})x_{n-i}.$$

The next result is an immediate consequence of Theorem 4.3.1, and may be compared with Corollary 4.2.2.

Corollary 4.3.2. *The origin is a globally asymptotically stable fixed point of the equation*

$$x_n = x_{n-k}g(x_{n-1}, \dots, x_{n-m}), \quad 1 \leq k \leq m$$

where $g \in C(\mathbb{R}^m, \mathbb{R})$, if $|g(X)| < 1$ for all $X \neq (0, \dots, 0)$.

As a simple application of Corollary 4.3.2, note that the equation

$$x_n = ax_{n-k} \exp[-b(x_{n-1}^2 + \dots + x_{n-m}^2)], \quad |a| \leq 1, b > 0$$

has a globally asymptotically stable fixed point at the origin. When $k = m$ and $|a| = 1$, then the characteristic polynomial of this equation is $\lambda^m - a = 0$. Therefore, every eigenvalue lies on the unit circle in this case. For $|a| < 1$ the global nature of asymptotic stability cannot be inferred from linearization alone.

Corollary 4.3.3. (Asymptotic stability) *Let A be open in Theorem 4.3.1. Then \bar{x} is asymptotically stable relative to $(\bar{x} - r, \bar{x} + r)$, where $r > 0$ is the largest real number such that $B_r(\bar{X}) \subset A$. In particular, if $A = \mathbb{R}^m$, then \bar{x} is globally asymptotically stable.*

Proof. Although the ball in the statement of the corollary is not closed, note that for r_0 in the proof of Theorem 4.3.1, $\partial B_{r_0}(\bar{X}) \subset B_r(\bar{X})$ if $X_0 \in B_r(\bar{X})$. Hence, $\Omega_0 \subset A$ and the rest of the proof of Theorem 4.3.1 is applicable.

Remark. Geometrically, Corollary 4.3.3 states that if the graph of f in \mathbb{R}^{m+1} lies within the complement of the closed polyhedral cone

$$C_{m+1}(\bar{x}) \doteq \{(u_1, \dots, u_{m+1}) : |u_{m+1} - \bar{x}| \geq \max\{|u_1 - \bar{x}|, \dots, |u_m - \bar{x}|\}\}$$

for all (u_1, \dots, u_m) in a deleted neighborhood of \bar{X} , then A is open and \bar{x} is attracting as in Corollary 4.3.3. See Figure 4.3.1.